

- 1) Solve the general solution to the following differential equation.

$$\frac{d^2x}{dt^2} + 2\frac{dx}{dt} + x = 4e^{-t} \ln(t) \quad (t > 0)$$

The characteristic equation is $r^2 + 2r + 1 = (r+1)^2 = 0$ with roots $r = -1, -1$. So, the homogeneous solution is

$$x_H(t) = c_1 e^{-t} + c_2 t e^{-t}.$$

To find a particular solution, we implement variation of parameters.

$$\begin{aligned} x_P(t) &= v_1(t)e^{-t} + v_2(t)te^{-t} \\ W[x_1, x_2](t) &= \begin{vmatrix} e^{-t} & te^{-t} \\ -e^{-t} & e^{-t} - te^{-t} \end{vmatrix} = e^{-2t} \\ v_1(t) &= - \int \frac{4te^{-2t} \ln(t)}{e^{-2t}} dt = -4 \int t \ln(t) dt = t^2 - 2t^2 \ln(t) \\ v_2(t) &= \int \frac{4e^{-2t} \ln(t)}{e^{-2t}} dt = 4 \int \ln(t) dt = 4t \ln(t) - 4t \\ x_P(t) &= (t^2 - 2t^2 \ln(t)) e^{-t} + (4t \ln(t) - 4t) te^{-t} \\ &= -3t^2 e^{-t} + 2t^2 e^{-t} \ln(t) \end{aligned}$$

So, the general solution is

$$x(t) = c_1 e^{-t} + c_2 t e^{-t} - 3t^2 e^{-t} + 2t^2 e^{-t} \ln(t).$$

- 2) Solve the general solution to the following differential equation.

$$\frac{d^2x}{dt^2} + x = \tan(t) \sec(t)$$

The characteristic equation is $r^2 + 1 = 0$ with roots $r = \pm i$. So, the homogeneous solution is

$$x_H(t) = c_1 \cos(t) + c_2 \sin(t).$$

To find a particular solution, we implement variation of parameters.

$$\begin{aligned} x_P(t) &= v_1(t) \cos(t) + v_2(t) \sin(t) \\ W[x_1, x_2](t) &= \begin{vmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{vmatrix} = 1 \\ v_1(t) &= - \int \frac{\tan(t) \sec(t) \sin(t)}{1} dt = - \int \tan^2(t) dt = - \int (\sec^2(t) - 1) dt = -\tan(t) + t \\ v_2(t) &= \int \frac{\tan(t) \sec(t) \cos(t)}{1} dt = \int \tan(t) dt = -\ln |\cos(t)| \\ x_P(t) &= (t - \tan(t)) \cos(t) - \ln |\cos(t)| \sin(t) \\ &= t \cos(t) - \sin(t) - \ln |\cos(t)| \sin(t) \end{aligned}$$

So, the general solution is

$$x(t) = c_1 \cos(t) + c_2 \sin(t) + t \cos(t) - \ln |\cos(t)| \sin(t)$$

where we drop the extra $-\sin(t)$ term from the particular solution since it can be absorbed into the homogeneous part of the solution.

- 3) A mass of size $m = 1$ is attached to a spring with strength $k = 10$. The coefficient of resistance for the system is $b = 2$, and an external force $F(t) = 10 \cos(4t)$ is acting on the system. Write down the differential equation that models the position of the mass $x = x(t)$ as measured from equilibrium. Find the *steady-state* portion of the solution (i.e. the particular solution).

The differential equation for this system is

$$\frac{d^2x}{dt^2} + 2\frac{dx}{dt} + 10x = 10 \cos(4t).$$

Since this is a damped oscillator and we are only asked for the steady-state solution $x_P(t)$, we don't need to find the homogeneous solution in this case (as it definitely won't be anything like the periodic forcing term). We can use Undetermined Coefficients for the particular solution.

$$\begin{aligned}x_P(t) &= A \cos(4t) + B \sin(4t) \\x'_P(t) &= 4B \cos(4t) - 4A \sin(4t) \\x''_P(t) &= -16A \cos(4t) - 16B \sin(4t)\end{aligned}$$

Substituting these into the differential equation gives

$$(-6A + 8B) \cos(4t) + (-6B - 8A) \sin(4t) = 10 \cos(4t).$$

So, we need

$$\begin{aligned}-6A + 8B &= 10 \\-6B - 8A &= 0.\end{aligned}$$

This gives $A = -\frac{3}{5}$ and $B = \frac{4}{5}$, and the steady-state solution is

$$x_P(t) = -\frac{3}{5} \cos(4t) + \frac{4}{5} \sin(4t).$$